

Single Fluid MHD

equations

• Equations to describe the plasma as a single fluid. Define mass velocity:

$$\vec{V} = \frac{m_i m_i \vec{v}_i + m_e m_e \vec{v}_e}{m_i m_i + m_e m_e} \quad (1)$$

• The current as:

$$\vec{j} = e (z m_i \vec{v}_i - m_e \vec{v}_e) \quad (2)$$

• The density as:

$$\rho = m_i m_i + m_e m_e \quad (3)$$

• We also need continuity:

$$\frac{\partial m_e}{\partial t} = - \vec{\nabla} \cdot (m_e \vec{v}_e) \quad (4)$$

$$\frac{\partial m_i}{\partial t} = - \vec{\nabla} \cdot (m_i \vec{v}_i) \quad (5)$$

• Multiply (4) by m_e and (5) by m_i leads to:

$$\begin{cases} m_e \frac{\partial m_e}{\partial t} = - \vec{\nabla} \cdot (m_e m_e \vec{v}_e) \\ m_i \frac{\partial m_i}{\partial t} = - \vec{\nabla} \cdot (m_i m_i \vec{v}_i) \end{cases} \Rightarrow$$

$$\Rightarrow \frac{\partial}{\partial t} \underbrace{(m_e m_e + m_i m_i)}_{\rho} = - \vec{\nabla} \cdot \underbrace{(m_e m_e \vec{v}_e + m_i m_i \vec{v}_i)}_{\rho \vec{v}} \Leftrightarrow$$

$$\Leftrightarrow \boxed{\frac{\partial}{\partial t} \rho = - \vec{\nabla} \cdot (\rho \vec{v})}$$

• We also define the charge density as:

$$\sigma = e (m_i z - m_e)$$

• Multiply (4) by $-e$ and (5) by ze and add leads to:

$$\begin{cases} - \frac{\partial}{\partial t} e m_e = + \vec{\nabla} \cdot (e m_e \vec{v}_e) \\ \frac{\partial}{\partial t} z e m_i = - \vec{\nabla} \cdot (z e m_i \vec{v}_i) \end{cases} \Rightarrow$$

$$\frac{\partial}{\partial t} \underbrace{(z e m_i - e m_e)}_{\sigma} = - \underbrace{\vec{\nabla} \cdot (z e m_i \vec{v}_i - e m_e \vec{v}_e)}_{\vec{j}} \quad (\Rightarrow)$$

$$\Rightarrow \frac{\partial \sigma}{\partial t} = - \vec{\nabla} \cdot \vec{j} \quad \Rightarrow \quad \boxed{\frac{\partial \sigma}{\partial t} + \vec{\nabla} \cdot \vec{j} = 0}$$

• Approximations:

$$- \quad 1 \gg \underbrace{\frac{z m_e}{m_i}}$$

$$\left| \frac{\frac{q_i}{m_i}}{\frac{q_e}{m_e}} \right| = \frac{\frac{z e}{m_i}}{\frac{e}{m_e}} = \frac{z e}{m_i} \frac{m_e}{e} = \frac{z m_e}{m_i}$$

$$- \quad m_e = z m_i \equiv m \quad (\text{quasi-neutral plasma})$$

(this does not mean that σ is zero! $\sigma \ll n_e e$)

• Equations for $\vec{v}$ and $\vec{j}$ become:

$$\left\{ \begin{array}{l} \vec{v} = \vec{v}_i + \frac{m_e z \vec{v}_e}{m_i} \end{array} \right. \quad (6)$$

or

$$\left\{ \begin{array}{l} \vec{j} = e n_e (\vec{v}_i - \vec{v}_e) \end{array} \right. \quad (7)$$

$$\bullet \quad -\frac{\vec{j} + e m_e \vec{v}_i}{e m_e} = \vec{v}_e \quad \Leftrightarrow \quad \vec{v}_e = \vec{v}_i - \frac{\vec{j}}{e m_e} \quad (\text{from (7)})$$

$$\bullet \quad \vec{v} - \frac{m_e z}{m_i} \vec{v}_e = \vec{v}_i \quad \Leftrightarrow \quad \vec{v} - \frac{m_e z}{m_i} \left(\vec{v}_i - \frac{\vec{j}}{e m_e} \right) = \vec{v}_i \quad \Leftrightarrow$$

$$\Leftrightarrow \quad \vec{v}_i \left(1 + \frac{m_e z}{m_i} \right) = \vec{v} + \frac{m_e z}{m_i m_e e} \vec{j} \quad (8)$$

• and, using (8):

$$\vec{v}_e = \vec{v} + \left(\frac{m_e z}{m_i m_e e} - \frac{1}{e m_e} \right) \vec{j}$$

• Equation of motion neglecting $\vec{v} \cdot \nabla \vec{v}$ (linear equations in $\vec{v}$) and also neglecting viscosity tensor (assume stress tensor leading to isotropic pressure term)

$$m_i m_i \frac{\partial v_i}{\partial t} = z e m_i (\vec{E} + \vec{v}_i \times \vec{B}) - \vec{\nabla} p_i + m_i m_i \vec{g} + \left. \frac{\partial p_{i-e}}{\partial t} \right|_{\text{all}} \quad (9)$$

$$m_e m_e \frac{\partial v_e}{\partial t} = -e m_e (\vec{E} + \vec{v}_e \times \vec{B}) - \vec{\nabla} p_e + m_e m_e \vec{g} + \left. \frac{\partial p_{e-i}}{\partial t} \right|_{\text{all}} \quad (10)$$

Add Eq. (9) and (10):

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$$m_i m_i \frac{d\vec{v}_i}{dt} + m_e m_e \frac{d\vec{v}_e}{dt} = \vec{E} \left(\underbrace{ze m_i - m_e}_{=0} \right) + (ze m_i \vec{v}_i - e m_e \vec{v}_e) \times \vec{B} +$$

$$+ (m_i m_i + m_e m_e) \vec{g} - \vec{\nabla} P$$

• E-field cancels out

$$\cdot \left(\frac{\partial p_{e,i}}{\partial t} \right)_{\text{all}} = - \left(\frac{\partial p_{i,e}}{\partial t} \right)_{\text{all}}$$

$$\cdot \vec{p} = \vec{p}_i + \vec{p}_e$$

Using Eqs. (5) and (1) leads to:

$$m_i m_i \frac{d}{dt} \left[\vec{v} + \frac{m_e}{m_i n_e e} \vec{j} \right] + m_e n_e \frac{d}{dt} \left[\vec{v} - \frac{\vec{j}}{n_e e} \right] = \underbrace{ze m_i (\vec{v}_i - \vec{v}_e)}_{\vec{j}} \times \vec{B} +$$

$$+ m_e \vec{g} - \vec{\nabla} P \quad (\Rightarrow)$$

$$(\Rightarrow) \underbrace{(m_i m_i + m_e m_e)}_{=P} \frac{d\vec{v}}{dt} + \underbrace{m_i \frac{d}{dt} \left(\frac{m_e}{n_e e} \vec{j} \right) - m_i \frac{d}{dt} \left(\frac{\vec{j} m_e}{n_e e} \right)}_{=0} = \vec{j} \times \vec{B} +$$

$$+ m_e \vec{g} - \vec{\nabla} P \quad (\Rightarrow)$$

$$P \frac{d\vec{v}}{dt} = \vec{j} \times \vec{B} + m_e \vec{g} - \vec{\nabla} P$$

(1)

Multiply (9) by ez/m_i and (10) by $-e/me$ and add:

(6)

$$\begin{aligned}
 \underbrace{ez m_i \frac{d\vec{v}_i}{dt} - e m_e \frac{d\vec{v}_e}{dt}}_{\text{first term}} &= \underbrace{\left(\frac{e^2 z^2 m_i}{m_i} + \frac{e^2 m_e}{m_e} \right)}_{\text{second term}} \vec{E} + \\
 &+ \underbrace{\left(\frac{e^2 z^2 m_i}{m_i} \vec{v}_i + \frac{e^2 m_e}{m_e} \vec{v}_e \right)}_{\text{third term}} \times \vec{B} - \\
 &- \underbrace{\frac{ez}{m_i} \vec{\nabla} p_i + \frac{e}{m_e} \vec{\nabla} p_e}_{\text{fourth term}} + \underbrace{(ez m_i - m_e e) \vec{g}}_{\text{fifth term}} + \\
 &+ \underbrace{\left(\frac{ez}{m_i} \frac{dp_{e-i}}{dt} \right)_{\text{coll}} - \left(\frac{e}{m_e} \frac{dp_{e-i}}{dt} \right)_{\text{coll}}}_{\text{sixth term}}
 \end{aligned}$$

From Eq. (2):

$$\begin{aligned}
 \vec{j} &= e (z m_i \vec{v}_i - m_e \vec{v}_e) = \\
 &= e z m_i (\vec{v}_i - \vec{v}_e) \Rightarrow \vec{j}/e z m_i = \vec{v}_i - \vec{v}_e
 \end{aligned}$$

Hence the first term is:

$$e z m_i \frac{d\vec{v}_i}{dt} - e m_e \frac{d\vec{v}_e}{dt} = e z m_i \frac{d\vec{v}_i - \vec{v}_e}{dt} = m_i \frac{d(\vec{j}/m_i)}{dt} = \boxed{n \frac{d}{dt} \left(\frac{\vec{j}}{n} \right)}$$

The second term is:

$$\left(\frac{e^2 z^2 m_i}{m_i} + \frac{e^2 m_e}{m_e} \right) \vec{E} = e^2 z m_i \left(\frac{z}{m_i} + \frac{1}{m_e} \right) \vec{E} = \frac{e^2 z m_i}{m_e} \vec{E} = \boxed{\frac{e^2 m}{m_e} \vec{E}}$$

The third term is:

$$\begin{aligned}
 & \left(\frac{e^2 z^2}{m_i} m_i \vec{v}_i + \frac{e^2 m_e}{m_e} \vec{v}_e \right) \times \vec{B} = \\
 & = \left[\frac{e^2 z^2}{m_i} m_i \left(\vec{v} + \frac{m_e z}{m_i m_e e} \vec{j} \right) + \frac{e^2 m_e}{m_e} \left(\vec{v} - \frac{\vec{j}}{e m_e} \right) \right] \times \vec{B} = \\
 & = \left(\frac{e^2 z^2 m_i}{m_i} + \frac{e^2 m_e}{m_e} \right) \vec{v} \times \vec{B} + \left(\frac{e^2 z^2 m_i m_e z}{m_i^2 m_e e} - \frac{e^2 m_e}{m_e m_e e} \right) \vec{j} \times \vec{B} \approx \\
 & \approx e^2 z m_i \left(\frac{z}{m_i} + \frac{1}{m_e} \right) \vec{v} \times \vec{B} + m_e e \left(\frac{z^2}{m_i^2} - \frac{1}{m_e^2} \right) \vec{j} \times \vec{B} \approx \\
 & \approx \boxed{\frac{e^2 m}{m_e} \vec{v} \times \vec{B} - \frac{e}{m_e} \vec{j} \times \vec{B}}
 \end{aligned}$$

The fourth term is:

$$-\frac{e z}{m_i} \vec{\nabla} p_i + \frac{e}{m_e} \vec{\nabla} p_e \approx \boxed{\frac{e}{m_e} \vec{\nabla} p_e}$$

The fifth term is:

$$(z m_i - m_e e) g \approx \boxed{0}$$

The sixth term is:

$$\left. \frac{e}{m_i} \frac{\partial p_{e-i}}{\partial t} \right|_{\text{all}} - \left. \frac{e}{m_e} \frac{\partial p_{e-i}}{\partial t} \right|_{\text{all}} = \frac{e}{m_i} \alpha (\vec{v}_e - \vec{v}_i) + \frac{e}{m_e} \alpha (\vec{v}_e - \vec{v}_i)$$

$$= \frac{e}{m_e} \alpha (\vec{v}_e - \vec{v}_i) \approx \boxed{-\frac{\alpha \vec{j}}{m_e n}} \quad ; \quad \alpha = n_e m_e v_{e-i}$$

Divide all terms by $e^+ m / m_e$ and put together:

$$\frac{m_e}{e^+} \frac{\partial}{\partial t} \left(\frac{\vec{j}}{n} \right) = \vec{E} + \vec{v} \times \vec{B} - \frac{e}{m_e} \frac{m_e}{m_e^2} \vec{j} \times \vec{B} + \frac{e}{m_e} \frac{m_e}{m_e^2} \vec{\nabla} p_e$$

$$+ \frac{\alpha}{m_e n} \frac{m_e}{m_e^2} \alpha \vec{j} =$$

$$= \vec{E} + \vec{v} \times \vec{B} - \frac{1}{m_e} \vec{j} \times \vec{B} + \frac{1}{m_e} \vec{\nabla} p_e - \underbrace{\frac{\alpha}{m_e^2 n}}_{\eta \text{ (viscosity)}} \vec{j}$$

$$\frac{\alpha}{n^2 e^+} = \frac{n m_e v_{e-i}}{n^2 e^+} = \frac{m_e}{n^+ e^+} v_{e-i} \equiv \eta$$

In a steady state:

$$\underbrace{\vec{E} + \vec{v} \times \vec{B}}_{\text{generalized Ohm's Law}} = \frac{1}{m_e} \overbrace{(\vec{j} \times \vec{B} + \vec{\nabla} p_e)}^{\text{Hall current}} + \eta \vec{j}$$

It is often the case that:

$$\boxed{\vec{E} + \vec{v} \times \vec{B} = \eta \vec{j}}$$

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The full set of MHD equations is then:

$$\rho \frac{\partial \vec{v}}{\partial t} = \vec{j} \times \vec{B} + m\rho \vec{g} - \nabla p \quad (11)$$

$$\vec{E} + \vec{v} \times \vec{B} = \eta \vec{j} \quad (12)$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0 \quad (13)$$

$$\frac{\partial \sigma}{\partial t} + \nabla \cdot \vec{j} = 0 \quad (14)$$

• Where are these equations important?

- Astrophysics

- Fusion

• Current research hot topic:

Can we recover the physics of MHD using
kinetic equations?